Comparison Theorems for ODEs and Their Application to Geometry of Weingarten Hypersurfaces

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Differential Geometry and Tanaka Theory -Differential System and Hypersurface Theory-

Comparison Theorem A

Assume F(X, Y) satisfies $F(0, 1/y_0) > 0$ and $\partial F/\partial X < 0$ for X > 0. Solve the following equations with the initial conditions $x(0) = x_0, \ y(0) = y_0, \ \alpha(0) = \overline{\alpha}(0) = 0.$

$$(I) \begin{cases} \frac{dx}{ds} = \cos \alpha, \\ \frac{dy}{ds} = \sin \alpha, \\ \frac{d\alpha}{ds} = F(\frac{\sin \alpha}{x}, \frac{\cos \alpha}{y}). \end{cases}$$
$$(II) \begin{cases} \frac{dx}{ds} = \cos \overline{\alpha}, \\ \frac{dy}{ds} = \sin \overline{\alpha}, \\ \frac{d\overline{\alpha}}{ds} = F(0, \frac{\cos \overline{\alpha}}{y}). \end{cases}$$

 $lpha(y) < \overline{lpha}(y)$ for all y satisfying $0 < lpha(y) < rac{\pi}{2}$

Comparison Theorem B

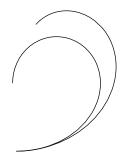
Assume $F(0, 1/y_0) > 0$ and $\partial F/\partial X$, $\partial F/\partial Y < 0$ for X, Y > 0. Solve the following equations with the initial conditions $x(0) = x_0, y(0) = y_0, \alpha(0) = \overline{\alpha}(0) = \alpha_0 = 0.$

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 $lpha(y) > \overline{lpha}(y)$ for all y satisfying $0 < lpha(y) < rac{\pi}{2}$



$$F(X,Y) = 1 - X - Y$$



Our Aim

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- ullet constant mean curvature hypersurfaces $\lambda_1+\dots+\lambda_n=$ const
- constant scalar curvature hypersurfaces $\sum_{i \neq j} \lambda_i \lambda_j =$ const
- hypersurfaces whose second fundamental form h have constant length $|h|^2 = \sum_i \lambda_i^2 = \! {\rm const}$

Delauney surfaces



Figure: unduloid

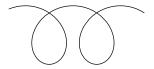
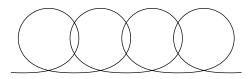


Figure: nodoid

A rotational surface with |h| = const



Noncompact Complete Hypersurfaces with Constant Scalar Curvature

Known Examples

- flat generalized cylinders
- ullet cylinders $S^p imes {f R}^{n-p}$
- 1-parameter family of rotational hypersurfaces (Leite, 1990)
- a complete hypersurface with constant negative scalar curvature in E^4 (O, 1989)
- a complete hypersurface with 0 scalar curvature in E^4 (Palmas,2000)
- a complete hypersurface with 0 scalar curvature in E^{2n} (Sato, 2000)

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Method

Method of equivariant geometry

We use a subgroup

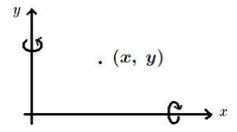
 $O(p+1) \times O(q+1) \subset O(p+q+2) = O(n+1)$ to construct Generalized rotational hypersurfaces. PDF \Rightarrow ODF

 $PDE \Rightarrow ODE$

 This method was used by W.Y. Hsiang et al. to construct many CMC hypersurfaces in the 80's.

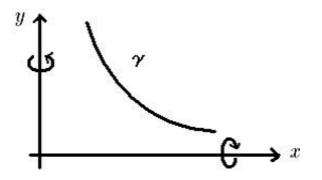
$O(p+1) \times O(q+1)$ -invariant hypersurfaces

- $O(p+1) imes O(q+1) \sim \mathrm{R}^{p+1} imes \mathrm{R}^{q+1}$
- The orbit space= the first quadrant ${f R}^2_+$
- The orbit through $(x, \; y) = S^p(x) imes S^q(y)$



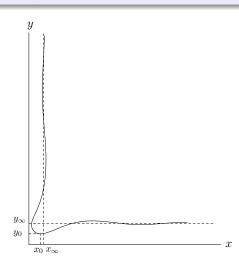
Generalized Rotational Hypersurfaces

 γ : a curve in the first quadrant ${f R}^2_+$ M_γ : O(p+1) imes O(q+1)-invariant hypersurface generated by γ



Main Theorem 1

There exists a new family of complete hypersurfaces $M^n \subset E^{n+1} \ (n \geq 5)$ with constant positive scalar curvature.



principal curvatures

$$x'y''-y'x'', \ rac{y'}{x}, \ -rac{x'}{y}$$
 : multiplicities $1, \ p, \ q$ (the curve is parametrized by the arc length)

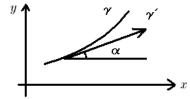
The scalar curvature of M_γ

$$egin{aligned} S &= & \sum_{i
eq j} \lambda_i \lambda_j \ &= & 2(x'y''-y'x'') \left(prac{y'}{x}-qrac{x'}{y}
ight) + p(p-1) \left(rac{y'}{x}
ight)^2 \ &+ q(q-1) \left(rac{x'}{y}
ight)^2 - 2pqrac{y'x'}{x}rac{y'}{y} \end{aligned}$$

Constant Scalar Curvature Equation

S = constant

$$(\mathbf{I}) \begin{cases} \frac{dx}{ds} = \cos \alpha, \\ \frac{dy}{ds} = \sin \alpha, \\ \frac{d\alpha}{ds} = \frac{p(p-1)\left(\frac{\sin \alpha}{x}\right)^2 - 2pq\frac{\sin \alpha}{x}\frac{\cos \alpha}{y} + q(q-1)\left(\frac{\cos \alpha}{y}\right)^2 - S}{2\left(q\frac{\cos \alpha}{y} - p\frac{\sin \alpha}{x}\right)}. \end{cases}$$

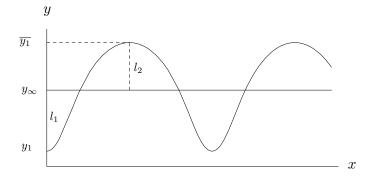


Comparison Equation

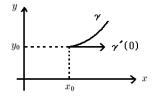
(I)
$$\begin{cases} \frac{dx}{ds} = \cos \alpha, \\ \frac{dy}{ds} = \sin \alpha, \\ \frac{d\alpha}{ds} = \frac{p(p-1)\left(\frac{\sin \alpha}{x}\right)^2 - 2pq\frac{\sin \alpha}{x}\frac{\cos \alpha}{y} + q(q-1)\left(\frac{\cos \alpha}{y}\right)^2 - S}{2\left(q\frac{\cos \alpha}{y} - p\frac{\sin \alpha}{x}\right)}. \end{cases}$$

(II)
$$\begin{cases} \frac{dx}{ds} = \cos \alpha, \\ \frac{dy}{ds} = \sin \alpha, \\ \frac{d\alpha}{ds} = \frac{q(q-1)\left(\frac{\cos \alpha}{y}\right)^2 - S}{2q\frac{\cos \alpha}{y}}. \end{cases}$$

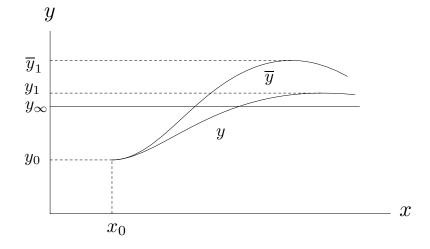
The solution of (II)



Comparison Theorem

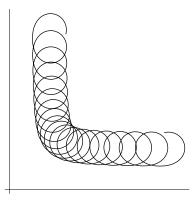


Comparison of Solution Curves



Main Theorem 2

There exists a new family of complete hypersurfaces $M^n \subset E^{n+1}$ $(n \ge 5)$ with |h| =const.



Comparison Theorem for $|h| = h_0$ (const)

Solve the following equations with the initial conditions $x(0) = x_0, \ y(0) = y_0, \ \alpha(0) = \overline{\alpha}(0) = \alpha_0.$

(I)
$$\begin{cases} \frac{dx}{ds} = \cos \alpha, \\ \frac{dy}{ds} = \sin \alpha, \\ \frac{d\alpha}{ds} = \sqrt{h_0^2 - p\left(\frac{\sin \alpha}{x}\right)^2 - q\left(\frac{\cos \alpha}{y}\right)^2}. \end{cases}$$

$$(\mathrm{II}) \begin{cases} \frac{dx}{ds} = \cos \alpha, \\ \frac{dy}{ds} = \sin \alpha, \\ \frac{d\alpha}{ds} = \sqrt{h_0^2 - p \left(\frac{\sin \alpha}{x_0}\right)^2 - q \left(\frac{\cos \alpha_0}{y}\right)^2}. \end{cases}$$

$$\Rightarrow \quad lpha(y) > \overline{lpha}(y), \quad$$
when $\ 0 < lpha < rac{\pi}{2}$

Theorem (Ye, 1991) Let (M^{n+1}, g) be a Riemannian manifold. Suppose that p_0 is a nodegenerate critical point of the scalar curvature of M. Then there exists $r_0 > 0$, such that for all $\rho \in (0, r_0)$, the geodesic sphere $S_{\rho}(p_0)$ may be perturbed to a constant mean curvature hypersurface S_{ρ} with $H = 1/\rho$.

Theorem Let (M^{n+1}, g) be a Riemannian manifold. Suppose that p_0 is a nondegenerate critical point of the scalar curvature of M. Then there exists $r_0 > 0$, such that for all $\rho \in (0, r_0)$, the geodesic sphere $S_{\rho}(p_0)$ may be perturbed to a closed hypersurface S_{ρ} whose second fundamental form are of constant length \sqrt{n}/ρ .